

Machine independent optimization

machine independent optimization depends on only the arithmetic properties of the operations in the language and can be achieved using foll. criteria

- The code should be analyzed completely and use alternative equivalent sequence of source code that will produce a minimum amount of target code.
- use appropriate program structure in order to improve the efficiency of target code.
- From the source program eliminate the unreachable code.
- move two or more identical computations at one place and make use of the result instead of each time computing the expressions.

Semantic Preserving Transformations

- These are a number of ways in which a compiler can improve a program without changing the function it computes.
- Common subexpression elimination, copy propagation, dead code elimination, and constant folding are common examples of such function-preserving (or semantics-preserving) transformations.
- Consider an example sorting program called quicksort to illustrate several important code-improving transformations.
- In this program $a[0]$ must contain the smallest of the sorted elements and $a[\text{max}]$ contains the largest element.

C Code for quicksort

```

void quicksort (int m, int n)
/* recursively sorts a[m] through a[n] */
{
  int i, j;
  int v, x;
  if (n <= m) return;
  /* fragment begins here */
  i = m - 1;
  j = n;
  v = a[n];
  while (1) {
    do i = i + 1; while (a[i] < v);
    do j = j - 1; while (a[j] > v);
    if (i >= j) break;
    x = a[i];
    a[i] = a[j]; /* swap a[i], a[j] */
    a[j] = x;
  }
  x = a[i];
  a[i] = a[n]; /* swap a[i], a[n] */
  a[n] = x;
  /* fragment ends here */
  quicksort (m, j);
  quicksort (i + 1, n);
}

```

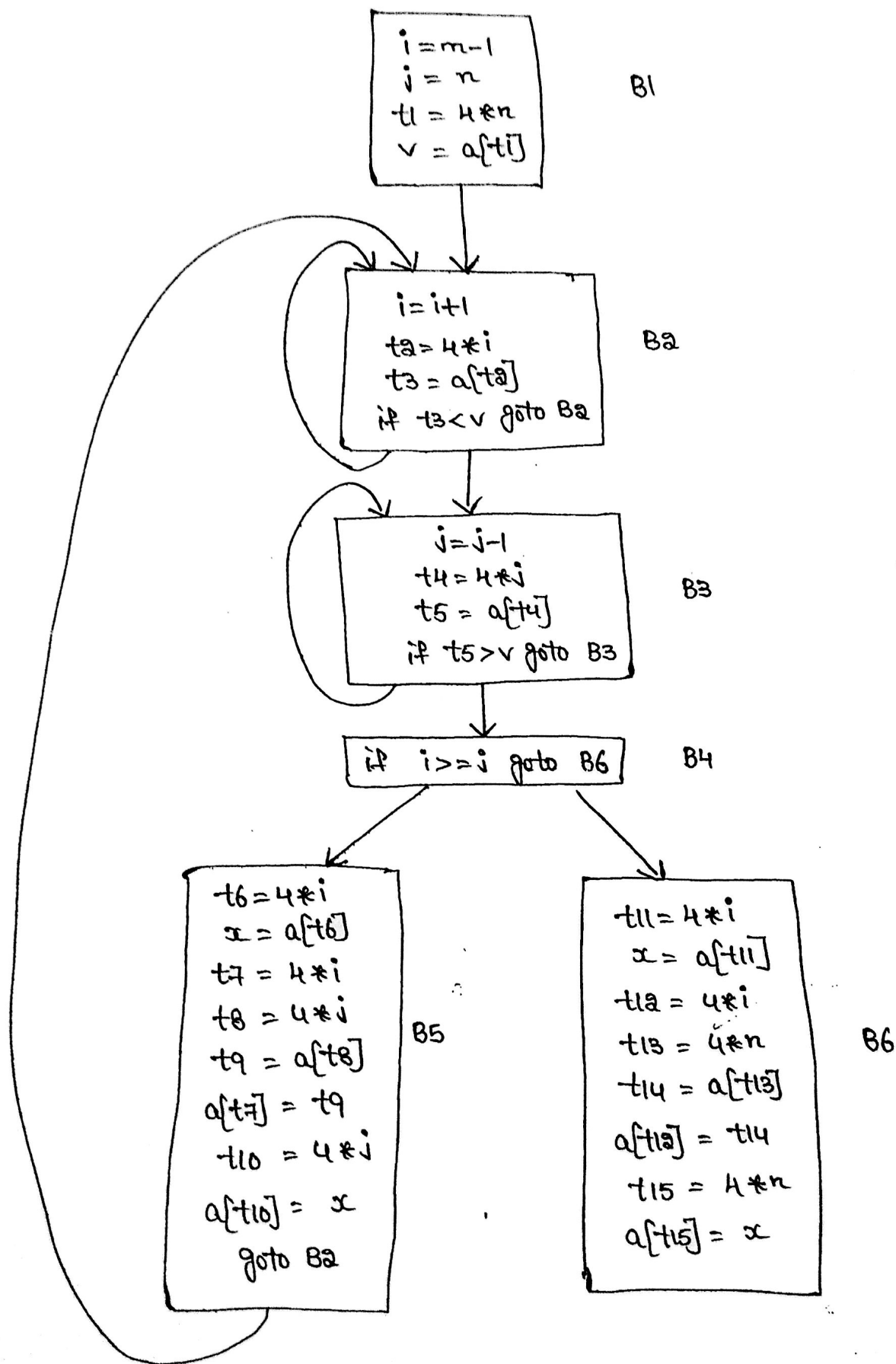
- Intermediate representation consists of three-address statements, where temporary variables are used to hold all the results of intermediate expressions.
- In this example we assume that integers occupy 4 bytes.
- The 3-address statements for quicksort program is as follows :-

Three-address code for quicksort

①	$r = r_1$	(6) $r_1 = r * i$
②	$r = r$	(7) $r_2 = r * i$
③	$r_1 = r * r_1$	(8) $r_1 = a[r_1]$
④	$r_2 = r * r_2$	(9) $a[r_1] = r_2$
⑤	$r = r_1$	(10) $r_2 = r * i$
⑥	$r_1 = r * r_1$	(11) $a[r_2] = r$
⑦	$r_2 = r * r_2$	(12) goto (5)
⑧	$r_1 = r_1 < r_2$ (5)	(13) $r_1 = r * i$
⑨	$r = r_1$	(14) $r = a[r_1]$
⑩	$r_1 = r * r_1$	(15) $r_2 = r * i$
⑪	$r_2 = r * r_2$	(16) $r_2 = r * r$
⑫	$r_1 = r_1 < r_2$ (2)	(17) $r_1 = a[r_2]$
⑬	$r_2 = r_1 < r_2$ (3)	(18) $a[r_1] = r_2$
⑭	$r = r * r_1$	(19) $r_2 = r * r$
⑮	$r = a[r_2]$	(20) $a[r_2] = r$

- The following is the flowgraph for the quicksort program.
- Block B1 is the entry node.
- There are 3 loops. Blocks B2 and B3 are loops by themselves.
- Blocks B2, B3, B4 and B5 together form a loop, with B2 the only entry point.

Flow graph for the quicksort



Common subexpression Elimination

3

An occurrence of an expression E is called a common subexpression if E was previously computed and the values of variables in E have not changed since the previous computation. We can avoid recomputing the expression, if we can use the previously computed value.

Example

- ① The assignments to t_7 and t_{10} have the common subexpressions $4*i$ and $4*j$ respectively on RHS. They have been eliminated by using t_6 instead of t_7 and t_8 instead of t_{10} in the block B5.

After eliminating t_7 and t_{10} , the block B5 is

$t_6 = 4*i$	$t_7 = t_6$
$x = a[t_6]$	
$t_8 = 4*j$	$t_{10} = t_8$
$t_9 = a[t_8]$	
$a[t_6] = t_9$	B5
$a[t_8] = x$	
goto B2	

- ② The assignments to t_{12} and t_{15} have the common subexpressions $4*i$ and $4*n$ respectively on RHS. They have been eliminated by using t_{11} instead of t_{12} and t_{13} instead of t_{15} in the block B6.

After eliminating t_{12} and t_{15} , the block B6 is

$t_{11} = 4*i$	
$x = a[t_{11}]$	
$t_{13} = 4*n$	
$t_{14} = a[t_{13}]$	
$a[t_{11}] = t_{14}$	B6
$a[t_{13}] = x$	

After local common subexpressions are eliminated, B5 still evaluates $u * i$ and $u * j$. They have eliminated, by using t_2 instead of t_6 and t_4 instead of t_8 .

After eliminating t_6 and t_8 , block B5 is

```

x = a[t2]
t9 = a[t4]
a[t2] = t9
a[t4] = x
goto B2

```

B5

$t_2 = u * i \rightarrow B_2$
 $t_4 = u * j \rightarrow B_3$
 $t_6 = t_2$
 $t_8 = t_4$

The common subexpressions t_{11} and t_{13} have been eliminated, by using t_2 instead of t_{11} and t_1 instead of t_{13} .

After eliminating t_{11} and t_{13} , block B6 is

```

x = a[t2]
t14 = a[t1]
a[t2] = t14
a[t1] = x

```

B6

$t_2 = u * i \rightarrow B_2$

B5 and B6 still having common subexpressions i.e, $t_9 = a[t_4]$ in B5 and $t_5 = a[t_4]$ in B3, and $t_3 = a[t_2]$ in B2 and $x = a[t_2]$ in B5

∴

```

x = t3
a[t2] = t5
a[t4] = x
goto B2

```

B5

Now in B6 the common subexpression is $x = a[t_2]$ in B6 and $t_3 = a[t_2]$ in B2 then block B6 becomes

```

x = t3
t14 = a[t1]
a[t2] = t14
a[t1] = x

```

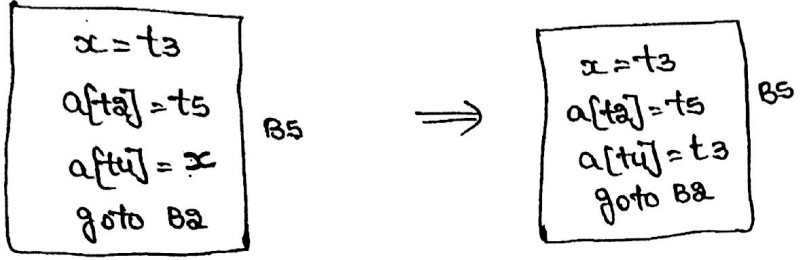
B6

COPY Propagation

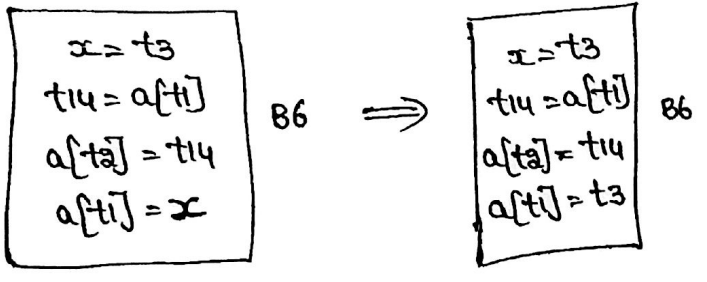
- The form $f = g$ called COPY statements or copies.
- The idea behind the COPY Propagation transformation is to use 'g' for 'f' wherever possible after the COPY statement $f = g$.

Example

① The assignment $x = t3$ in Block B5 is a COPY statement, then COPY-Propagation applied to B5 yields,



② The assignment $x = t3$ in Block B6 is a COPY statement, then COPY-Propagation applied to B6 yields,

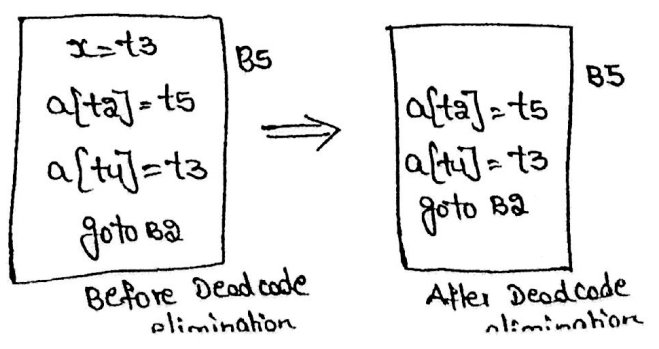


Dead Code Elimination

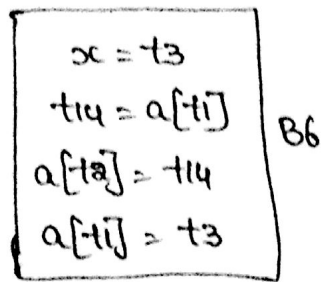
A variable is live at a point in a program if its value can be used subsequently, otherwise it is dead at that point, i.e, statements that compute values that never get used.

Example

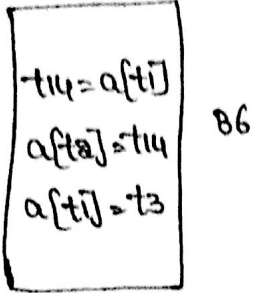
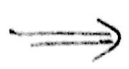
① The assignments $x = t3$ in Block B5 is a dead code. Dead code elimination applied to B5 yields



The assignment $x = t3$ in Block B6 is a deadcode. After eliminating deadcode B6 is



Before deadcode elimination



After deadcode elimination

Constant Folding

- The substitution of values for names whose values are constant is known as constant folding.
- In the folding technique the computation of constant is done at compile time instead of execution time.

Example

① for the statement

$length = \left(\frac{aa}{7}\right) * d$
--

Here folding is implied by performing the computation of $\left(\frac{aa}{7}\right)$ at compile time instead of execution time.

Loop Optimization

④

The running time of a program may be improved if we decrease the number of instructions in an inner loop, even if we increase the amount of code outside that loop.

These are ~~three~~⁶ techniques in loop optimizations.

- 1) code motion
- 2) Induction variable elimination
- 3) Reduction in strength
- ④ Loop unrolling
- ⑤ Loop fusion
- ⑥ Loop invariant method.

1) Code motion

Code motion moves code outside a loop. This transformation takes an expression that yields the same result independent of the number of times a loop is executed (a loop-invariant computation) and places the expression before the loop.

Example

Consider the statement

```
while(i <= limit - 2)
```

Evaluation of $limit - 2$ is a loop-invariant computation.

Code motion will result in the equivalent of,

```
t = limit - 2
while(i <= t)
```

2) Induction variable Elimination

Induction variable is a variable of the form,

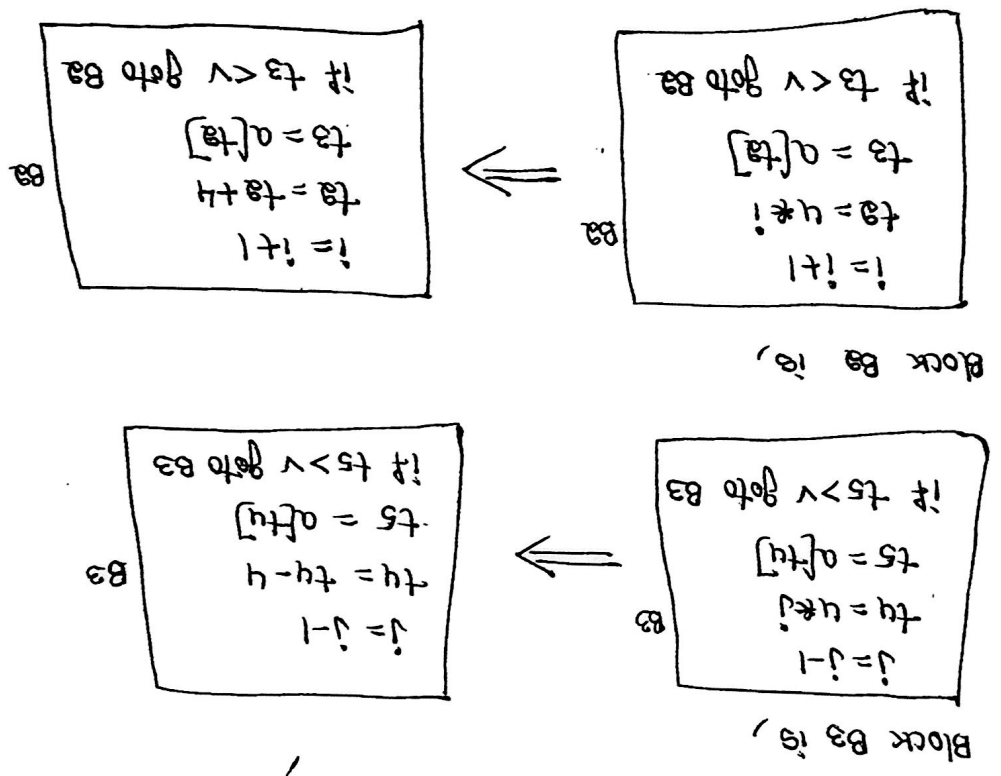
```
Vi = ± C1
Vi = Vi ± C2
```

where C_1, C_2 are constants.

Example

The values of i and t_4 remain in lock-step in B_3 . Every time the value of i decreases by 1, that of t_4 decreases by 4 because t_4 is assigned to t_4 .

Therefore replace the assignment $t_4 = t_4 - 4$ by $t_4 = t_4 - 4$. The only problem is that t_4 does not have a value when we enter block B_3 for the first time. Since we must maintain the relationship $t_4 = 4 * i$ on entry to the block B_3 , we place an initialization of t_4 at the end of the block where ' i ' itself is initialized.



3) Reduction in strength

The replacement of an expensive operation by a cheaper one is termed reduction in strength.

Example The multiplication step $t_3 = 4 * i$ in B_3 was replaced by an addition step $t_3 = t_3 + 4$.

This replacement will speed up the object code, if addition takes less time than multiplication, as in the case of many machines.

4) Loop unrolling

In this method the numbers of jumps and tests can be reduced by writing the code two times.

for example

```

int i=1;
while(i<=100)
{
  a[i]=b[i];
  i++;
}

```

Can be written as

```

int i=1;
while(i<=100)
{
  a[i]=b[i];
  i++;
  a[i]=b[i];
  i++;
}

```

5) Loop fusion

In loop fusion method several loops are merged to one loop.

for example

```

for i=1 to n do
  for j=1 to m do
    a[i,j]=10

```

Can be written as

```

for i=1 to n; j=1 to m do
  a[i,j]=10

```

6) Loop invariant method

In this optimization technique the computation inside the loop is avoided. for example

```

for i=0 to 10 do begin
  k=i+a/b;
  ---
  ---
end;

```

Can be written as

```

t=a/b
for i=0 to 10 do begin
  k=i+t;
  ---
  ---
end;

```

Instruction Scheduling

→ The order of three address code affects the cost of the object code being generated. By changing the order in which computations are done we can obtain the object code with minimum cost. Thus code optimization can be achieved by scheduling the instructions in proper order. This technique of code optimization is called instruction scheduling.

for example

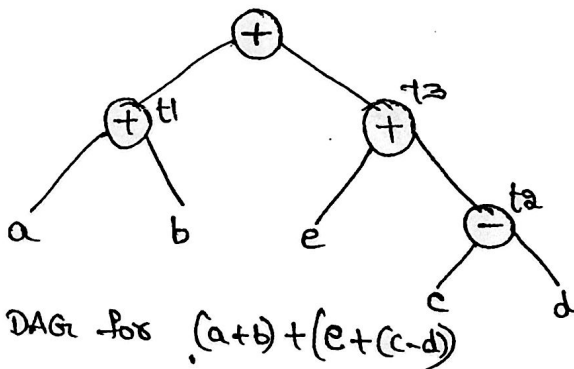
$$t1 = a + b$$

$$t2 = c - d$$

$$t3 = e + t2$$

$$t4 = t1 + t3$$

for the expression $(a+b) + (e+(c-d))$



The code can be generated by translating the three address code line by line.

```

MOV a, R0
ADD b, R0    /* R0 = a+b */
MOV c, R1
SUB d, R1    /* R1 = c-d */
MOV R0, t1   /* t1 = a+b */
MOV e, R0
ADD R0, R1   /* R1 = e+(c-d) */
MOV t1, R0   /* R0 = a+b */
ADD R1, R0   /* R0 = (a+b) + (e+(c-d)) */
MOV R0, t4

```

Now if we change the ordering sequence of the above three address code (3)

$$t_2 = c - d$$

$$t_3 = e + t_2$$

$$t_1 = a + b$$

$$t_4 = t_1 + t_3$$

Then we get an improved code as

MOV C, R0

SUB d, R0

MOV e, R1

ADD R0, R1

MOV a, R0

ADD b, R0

ADD R1, R0

MOV R0, t4

Thus optimized code can be obtained by instruction scheduling.

Interprocedural Optimization (IPO)

Inter-procedural optimization technique is a kind of code optimization in which collection of optimization techniques are used to improve the performance of the program that contain many frequently used functions or blocks. IPO reduces or eliminates duplicate calculations, inefficient use of memory and to simplify loops.

IPO may re-order the routines for better memory utilization. The compiler tests for branches that are never taken and removes the code in that branch.

IPO also checks if constants are used properly or not.

Consider the following flow graph to perform interprocedural optimizations (IPO) on the code.

